

Terminal de acesso para a televisão digital: validação do protótipo de laboratório.

André Luís Bacarin Gobo (IC)*, Altamiro Amadeu Susin

*andre.gobo@ufrgs.br



UFRGS PROPESQ **XXV SIC** Salão Iniciação Científica

ENG - Engenharias

INTRODUÇÃO

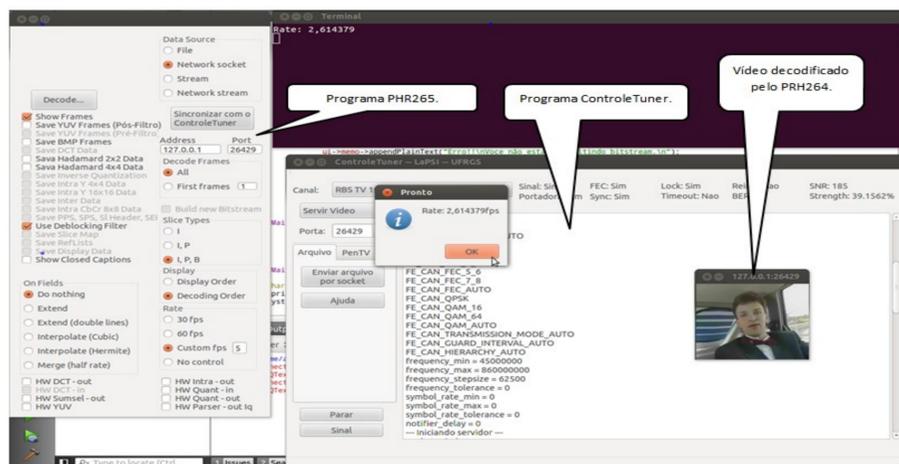
No LaPSI está sendo desenvolvido um SoC (system-on-chip) para controle de um set-top box compatível com o sistema brasileiro de televisão digital (SBTVD). Uma parte deste SoC é um decodificador de vídeo em hardware, que é compatível com o padrão H.264. O desenvolvimento está sendo feito em uma linguagem de descrição de hardware (VHDL) e o protótipo é validado em um kit de desenvolvimento com FPGA.

TESTES DO PRH264

O PRH264 é um software desenvolvido pelo LaPSI para servir como um decodificador de referência, por isso testes foram feitos para verificar o seu perfeito funcionamento. Os bitstreams utilizados nos testes foram gerados pelo programa JM (H.264/14496-10 AVC REFERENCE SOFTWARE), desenvolvido pela Joint Video Team, que serve de referência para gerar bitstreams de vídeo a partir de dados de vídeo sem compressão. Os testes feitos utilizando o JM são mostrados na tabela ao lado.

Resumo dos testes do PRH usando o programa de referência JM – Versão 1.1.1
Autor: André Luís Bacarin Gobo – LaPSI – Delet – UFRGS – Outubro de 2012
Versão utilizada: prh_codeblocks_Jonas_julho_2012_v3

Descrição – Parâmetro no encoder.cfg	BASELIN	MAIN-P	MAIN-B	HIGH
QP offset that will be used for coding Cb components-CbQPoffset	% % % % % % % % % % % % % % % %	% % % % % % % % % % % % % % % %	% % % % % % % % % % % % % % % %	% % % % % % % % % % % % % % % %
QP offset that will be used for coding Cr components-CrQPoffset	% % % % % % % % % % % % % % % %	% % % % % % % % % % % % % % % %	% % % % % % % % % % % % % % % %	% % % % % % % % % % % % % % % %
Frame in display order from which to apply the Change QP offsets – ChangeQPFrame	% % % % % % % % % % % % % % % %	% % % % % % % % % % % % % % % %	% % % % % % % % % % % % % % % %	% % % % % % % % % % % % % % % %
Subpixel Motion Estimation – DisableSubpelME	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
Weighting for chroma components – ChromaMEWeight	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
Intra prediction modes for Inter (P or B) slices – DisableIntraInInter	0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
P-INTER*	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
P- SKIP – P-Skip	0 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
INTRA*	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
0-only 4x4 transform, 1: 8x8 transform additionally, 2: only 8x8 transform – Transform8x8Mode	% % % % % % % % % % % % % % % %	% % % % % % % % % % % % % % % %	% % % % % % % % % % % % % % % %	% % % % % % % % % % % % % % % %
FILTR0*	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
RD-optimized mode decision – RDOptimization	x x x 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	x x x 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	x x x 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	x x x 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
based mode decision for Intra 16x16 MB – I16RDOpt	x x x 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	x x x 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	x x x 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	x x x 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Submacroblock coding state – SubMBCodingState	x x x 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	x x x 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	x x x 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	x x x 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2
Lagrangian parameters – UseExplicitLambdaParams	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
Update lambda given Chroma ME consideration – UpdateLambdaChromaME	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
Adaptive rounding based on JVT_N011 – AdaptiveRounding	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
Coefficient rounding adaptation for chroma – AdaptRndChroma	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
Explicit Offset Quantization Matrices – OffsetMatrxPresenFlag	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
Adaptive Rounding Weight*	4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4	4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4	4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4	4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4
Motion estimation mode – SearchMode	x x x -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1	x x x -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1	x x x -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1	x x x -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1
Reduces Search range for ME based on references and/or block types. – SearchRange	% % % 32 32 32 32 32 32 32 32 32 32 32 32 32 32	% % % 32 32 32 32 32 32 32 32 32 32 32 32 32 32	% % % 32 32 32 32 32 32 32 32 32 32 32 32 32 32	% % % 32 32 32 32 32 32 32 32 32 32 32 32 32 32
Error metric*	% % % 1 1 1 3 3 3 3 3 3 3 3 3 3 3 2 2 2 2 2	% % % 1 1 1 3 3 3 3 3 3 3 3 3 3 3 2 2 2 2 2	% % % 1 1 1 3 3 3 3 3 3 3 3 3 3 3 2 2 2 2 2	% % % 1 1 1 3 3 3 3 3 3 3 3 3 3 3 2 2 2 2 2
Skip Deblocking for non-reference frames – SkipDeBlockNonRef	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
Calculate Color component interpolated values in advance and store them – ChromaMCBuffer	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
Considers Chroma components during motion estimation. – ChromaMEEnable	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
Direct Mode Inter Prediction & Motion Compensation in B Slices. – B-SliceDirect	% % % 0 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0 0 0 0	% % % 0 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0 0 0 0	% % % 0 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0 0 0 0	% % % 0 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0 0 0 0
B-INTER*	% % % 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
BiPredMotionEstimation*	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
BiPredictive motion estimation for 16x16 partitions in B Slices – BiPredSearch16x16	% % % 0 0 0 0 1 1 0 1 1 0 0 0 1 1 1 1 1 1 1	% % % 0 0 0 0 1 1 0 1 1 0 0 0 1 1 1 1 1 1 1	% % % 0 0 0 0 1 1 0 1 1 0 0 0 1 1 1 1 1 1 1	% % % 0 0 0 0 1 1 0 1 1 0 0 0 1 1 1 1 1 1 1
BiPredictive motion estimation for 8x8 partitions in B Slices – BiPredSearch8x8	% % % 0 0 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0	% % % 0 0 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0	% % % 0 0 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0	% % % 0 0 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0
BiPredictive motion estimation for 4x4 partitions in B Slices – BiPredSearch4x4	% % % 0 0 0 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0	% % % 0 0 0 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0	% % % 0 0 0 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0	% % % 0 0 0 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0
B coded pictures as references – ReferencePictures	% % % 0 0 0 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0	% % % 0 0 0 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0	% % % 0 0 0 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0	% % % 0 0 0 0 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0
B hierarchical coding – HierarchicalCoding	% % % 0 0 0 0 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0	% % % 0 0 0 0 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0	% % % 0 0 0 0 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0	% % % 0 0 0 0 0 0 0 0 1 1 0 0 0 0 0 0 0 0 0
QP based on hierarchy level – HierarchyLevelQPEnable	% % % 0 0 0 0 0 0 0 0 0 0 1 0 0 0 0 0 0 0 0	% % % 0 0 0 0 0 0 0 0 0 0 1 0 0 0 0 0 0 0 0	% % % 0 0 0 0 0 0 0 0 0 0 1 0 0 0 0 0 0 0 0	% % % 0 0 0 0 0 0 0 0 0 0 1 0 0 0 0 0 0 0 0
Encode using the Explicit Seq Coding (explicit_seq.cfg)-dã pra configurar - ExplicitSeqCoding	% % % 0 0 0 0 0 0 0 0 0 0 1 0 0 0 0 0 0 0 0	% % % 0 0 0 0 0 0 0 0 0 0 1 0 0 0 0 0 0 0 0	% % % 0 0 0 0 0 0 0 0 0 0 1 0 0 0 0 0 0 0 0	% % % 0 0 0 0 0 0 0 0 0 0 1 0 0 0 0 0 0 0 0
Low Delay hierarchical coding structure generation - LowDelay	% % % 1 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	% % % 1 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	% % % 1 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	% % % 1 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Performs ref. Pic. list reordering for P coded frames based on POC values – ReferenceReorder	% % % 1 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	% % % 1 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	% % % 1 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	% % % 1 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Performs memory management control based on POC values – POCMemoryManagement	% % % 1 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	% % % 1 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	% % % 1 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	% % % 1 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Set first frame as long term - SetFirstAsLongTerm	% % % 0 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	% % % 0 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	% % % 0 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	% % % 0 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Entropy Coding method 0->UVLC 1->CABAC - SymbolMode	% % % 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	% % % 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	% % % 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	% % % 0 0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
CABAC context initialization method – ContextIniMethod	% % % 0 0 x 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	% % % 0 0 x 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	% % % 0 0 x 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	% % % 0 0 x 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Entrelaçado*	% % % n n n n n n n n n n n n n n n n n n n	% % % n n n n n n n n n n n n n n n n n n n	% % % n n n n n n n n n n n n n n n n n n n	% % % n n n n n n n n n n n n n n n n n n n
WeightYCoCrRD0*	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
WeightPIME/DC*	% % % 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
Weighted prediction for B slices - WeightedBiPrediction	% % % 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
Use DC Iterative Motion compensated based weighted prediction method – WPIterMC	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
Use LMS method for B slice weighted prediction – EnhancedBWeightSupport	% % % 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
Improved Motion Compensation Precision using WP based methods – WPMCPrecision	% % % 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
Performs multiple pass coding and make RD optimal decision among them – RDPictureDecision	% % % 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 0 0 0 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
Transmit multiple parameter sets – GenerateMultiplePPS	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	% % % 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
Rate Distortion Optimized Quantization*	ok[E] E1 E2 E3 E1 ok[E] E2 E2 E2 E4 E4 ok[E] E1 E5 E5	ok[E] E1 E2 E3 E1 ok[E] E2 E2 E2 E4 E4 ok[E] E1 E5 E5	ok[E] E1 E2 E3 E1 ok[E] E2 E2 E2 E4 E4 ok[E] E1 E5 E5	ok[E] E1 E2 E3 E1 ok[E] E2 E2 E2 E4 E4 ok[E] E1 E5 E5



RESULTADOS

A automatização do ControleTuner aumentou consideravelmente a rapidez e praticidade de cada teste, pois agora para realiza-lo basta executar 4 passos, antes eram 9, e além disso foram adicionadas caixas de dialogo para reduzir o erro de operação da placa. Além disso a tabela feita a partir dos testes do PRH264 foi de grande ajuda para o aperfeiçoamento e ajuste do programa, pois com ela foi possível identificar o erro e corrigi-lo de maneira mais rápida. A figura acima mostra o PRH264 funcionando junto com o ControleTuner.



TESTES EM PLACA

O ControleTuner é um software que recebe, por meio de um pentv, bitstreams transmitidos por emissoras através do ar e os retransmite ao PRH264 ou à placa de prototipação por uma interface de rede. A placa FPGA ML509 implementa o circuito do decodificador H264 "Intra-only", o qual consegue decodificar quadros I do perfil Baseline. A imagem ao lado mostra a placa ML509 e a imagem que ela decodificou. O bitstream foi captado da emissora através do ControleTuner e transmitido para a placa através do cabo Ethernet (cabo azul). Com a necessidade de verificar o funcionamento dos módulos implementados pela equipe foi preciso avaliar uma grande gama de parâmetro do decodificador da televisão digital. Assim, o ControleTuner foi aperfeiçoado para que o procedimento de teste ficasse mais rápido e prático comparado ao que era antes. A integração entre o ControleTuner e o PRH também foi realizada para verificar e observar transmissões de emissoras sem a utilização da placa.



MODALIDADE DE BOLSA

Iniciação Científica